

MEM6810 Engineering Systems Modeling and Simulation

工程系统建模与仿真

Theory Analysis

Lecture 5: Input Modeling

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(Sino-US Global Logistics Institute)



- 1 Introduction
- 2 Data Collection
- 3 Identifying Distribution
 - ▶ Physical Basis of Distributions
 - ▶ Histogram and Bar Chart
- 4 Distribution Fitting
 - ▶ Method of Moments
 - ▶ A Simple Variation of MoM
 - ▶ Maximum Likelihood Estimation
- 5 Goodness of Fit
 - ▶ Graphical Methods
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- 6 An Illustrative Example

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- The quality of outputs is no better than the quality of inputs.
 - *“Garbage in, garbage out.”*
- *“All models are wrong, but some are useful.”* – George Box.
 - There is no “true” model for any stochastic input.
 - The best we can do is to obtain an approximation that yields reasonable and useful results.

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 - can capture the physical properties of the system;
 - can be easily tuned to the situation at hand;
 - can be efficiently generated with certain random variate generation technique.
- Input modeling is sometimes more of an art than an engineering.
 - It nearly always requires the analysts to use their judgment as well as to apply appropriate statistical tools.
 - Since there is no “true” model, it is sensible to run the simulation with several plausible input models to see if the conclusions are robust or highly sensitive to the choices.

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 - ④ Evaluate the chosen distribution and parameters for goodness of fit.
 - graphical methods: histogram, bar chart, quantile-quantile (Q-Q) plot, probability-probability (P-P) plot.
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 - ⑤ If the fit is not good, select another candidate and go to Step 3, or use an empirical distribution.

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- **Never** trust data blindly!
 - A common mistake is to simply throw data into a software and ask for a “best” fit model.
 - Always take into account under what context (e.g., time, potential influence of other factors) the data was collected.

- The collected data can be
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- Sometimes the effort or cost to transform data into a usable form, or “clean” data, can be as significant as that required to obtain them.

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 - Check for autocorrelation.
 - Collect input data, not output data.
 - Example: customer arrival times and service times are input, whereas waiting times are output.

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- Do not ignore the physical characteristics of the process when selecting distributions.
 - Is the process naturally discrete or continuous valued?
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- There are literally hundreds of probability distributions that have been created; many were created with some specific physical process in mind.

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 - *Example 1*: the number of customers that arrive to a store during 1 hour.
 - *Example 2*: the number of defects found in 30 square meters of sheet metal.

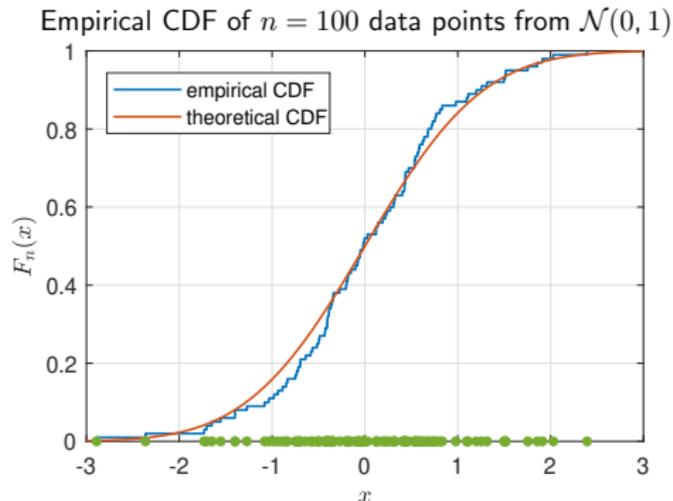
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 - **empirical distribution**: Often used when no theoretical distribution seems appropriate.

- The CDF of the **empirical distribution** (empirical CDF) is defined as

$$F_n(x) = \frac{\text{number of points } \leq x}{n} = \frac{1}{n} \sum_{i=1}^n \mathbb{1}_{\{x_i \leq x\}}.$$

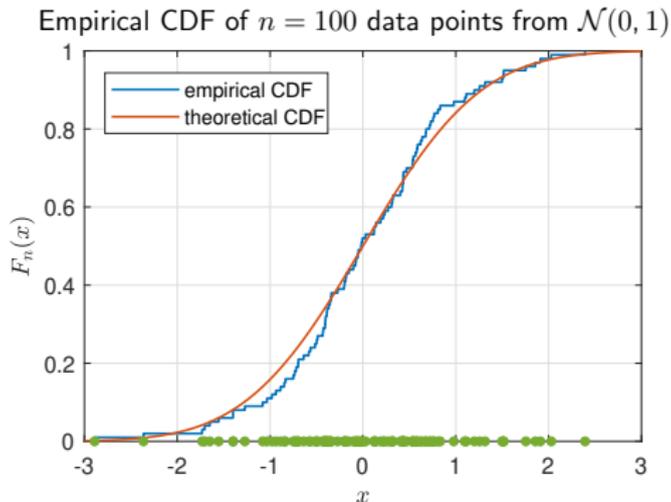
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- The empirical CDF is a right-continuous step function.

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 - **exponential**: Models the time between independent events, or a process time that is memoryless.
 - *Example 1*: the times between the arrivals from a large population of potential customers who act independently.
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 - **Weibull**: Models the time to failure for components.
 - *Note*: the failure rate can be increasing, decreasing, or constant (reduce to exponential distribution).

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 - **Erlang**: Models the time that can be viewed as the sum of several exponentially distributed times.
 - *Example*: a computer network fails when a computer and two backup computers fail, and each has exponentially distributed time to failure.
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 - *Note*: can be shifted away from 0 by adding a constant; can cover a range different from $[0, 1]$ by multiplying by a constant.
 - **triangular**: Models a process for which only the minimum, most likely, and maximum values of the distribution are known.
 - *Example*: only the minimum, most likely, and maximum time required to test a product are known.

- Useful in determining the shape of the distribution from which the data have been sampled:
 - **Histogram** describes frequency or relative frequency (i.e., ratio) of (usually continuous) data in different ranges.
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- For continuous data:
 - Histogram corresponds to the pdf of a theoretical distribution.
 - In terms of the *shape*, not the exact *value*![†]
- For discrete data:
 - Usually use bar chart instead of histogram.
 - Bar chart corresponds to the pmf of a theoretical distribution.
 - In terms of both the *shape* and *value* (if the bar chart uses relative frequency).

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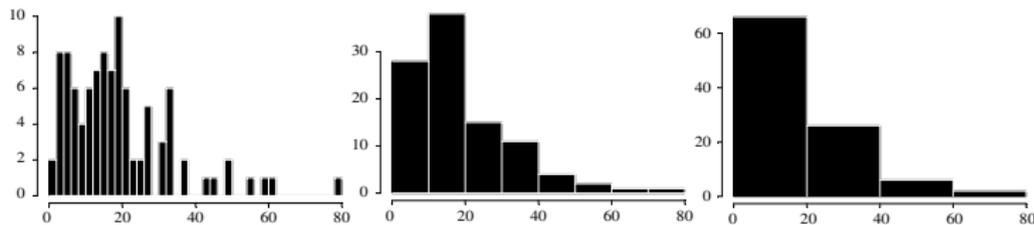


Figure: Ragged, Appropriate and Coarse Histograms (from [Banks et al. \(2010\)](#))

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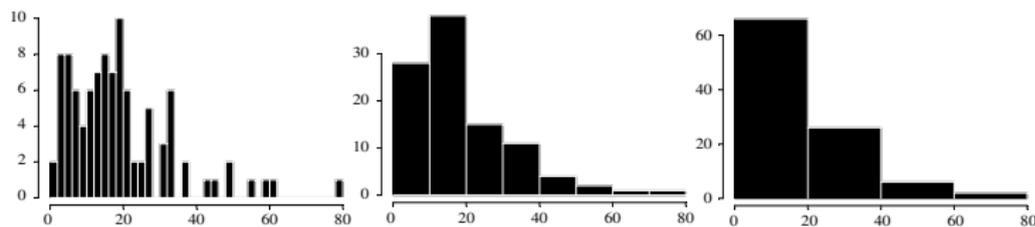


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- Choosing the number of intervals approximately equal to the square root of the sample size often works well in practice ([Hines et al. 2002](#)).

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 - Called distribution fitting, or parameter estimation.
- There are many different approaches and we discuss two simple ones:
 - method of moments (MoM)
 - maximum likelihood estimation (MLE)

- For a random variable X , its k th moment is defined as $\mathbb{E}[X^k]$.

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- Suppose the considered distribution family has s unknown parameters.
 - ① Analytically compute $\mathbb{E}[X^1], \dots, \mathbb{E}[X^s]$, as functions of those parameters.
 - *Note:* the moments of common distributions are well-known.
 - ② Compute m_1, \dots, m_s from the data.
 - ③ Solve $\mathbb{E}[X^k] = m_k$, $k = 1, \dots, s$, for s unknown parameters.

- Example 1: Suppose X_1, \dots, X_n are iid from $\text{Gamma}(\alpha, \lambda)$ (in shape & rate parametrization).
 - Recall: $f(x) = \frac{\lambda^\alpha}{\Gamma(\alpha)} x^{\alpha-1} e^{-\lambda x}$, $\mathbb{E}[X] = \alpha/\lambda$, $\text{Var}(X) = \alpha/\lambda^2$.
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Estimate α and λ using MoM.

Solution. The first two moments are

$$\mathbb{E}[X] = \alpha/\lambda = m_1,$$

$$\mathbb{E}[X^2] = \text{Var}(X) + (\mathbb{E}[X])^2 = (\alpha + \alpha^2)/\lambda^2 = m_2.$$

Solving two equations yields MoM estimators

$$\hat{\alpha} = \frac{m_1^2}{m_2 - m_1^2}, \quad \hat{\lambda} = \frac{m_1}{m_2 - m_1^2}. \quad \blacksquare$$

- Example 2: Suppose X_1, \dots, X_n are iid from $\text{Exp}(\lambda)$. Estimate λ using MoM.

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Solution. The first moment is

$$\mathbb{E}[X] = 1/\lambda = m_1.$$

So the MoM estimator of λ is $\hat{\lambda} = \frac{1}{m_1} = \frac{n}{X_1 + \dots + X_n}$. ■

- Example 3: Suppose X_1, \dots, X_n are iid from $\mathcal{N}(\mu, \sigma^2)$. Estimate μ and σ^2 using MoM.

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- Remark: $\hat{\mu} = \frac{\sum_{i=1}^n X_i}{n}$, and

$$\begin{aligned}\hat{\sigma}^2 &= \frac{X_1^2 + \dots + X_n^2}{n} - \bar{X}^2 = \frac{\sum_{i=1}^n X_i^2 - n\bar{X}^2}{n} \\ &= \frac{\sum_{i=1}^n (X_i - \bar{X})^2}{n}.\end{aligned}$$



- Many common distributions have no more than 2 parameters:
Ber(p), B(n, p), NB(r, p), Geo(p), Pois(λ), Unif[a, b], Exp(λ),
Erl(k, λ), Gamma(α, λ), Beta(α, β), Weibull(α, β), $\mathcal{N}(\mu, \sigma^2)$, t_p ,
 χ_p^2 .

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- Instead of using MoM, another convenient way to estimate the parameters is using sample mean \bar{X} and sample variance S^2 :

$$\bar{X} = \frac{\sum_{i=1}^n X_i}{n} = m_1,$$
$$S^2 = \frac{\sum_{i=1}^n (X_i - \bar{X})^2}{n-1} = \frac{\sum_{i=1}^n X_i^2 - n\bar{X}^2}{n-1} = \frac{n}{n-1}(m_2 - m_1^2),$$

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- Note 2: In original MoM, we solve $\text{Var}(X) = m_2 - m_1^2$.



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Recall: using MoM, $\hat{\alpha} = \frac{m_1^2}{m_2 - m_1^2}$, $\hat{\lambda} = \frac{m_1}{m_2 - m_1^2}$.

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- Remarks:
 - If X_1, \dots, X_n haven't been observed, $\lambda^* = n/(X_1 + \dots + X_n)$.
 - The estimator is the same as in MoM.



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- For discrete distributions, replace the pdf with pmf.



- 1 Introduction
- 2 Data Collection
- 3 Identifying Distribution
 - ▶ Physical Basis of Distributions
 - ▶ Histogram and Bar Chart
- 4 Distribution Fitting
 - ▶ Method of Moments
 - ▶ A Simple Variation of MoM
 - ▶ Maximum Likelihood Estimation
- 5 Goodness of Fit
 - ▶ Graphical Methods
 - ▶ Statistical Tests
 - ▶ Remarks
- 6 An Illustrative Example

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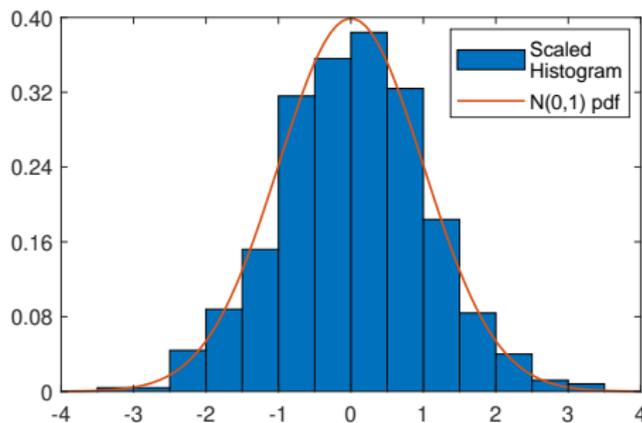


Figure: Example of Scaled Histogram (Empirical pdf) vs. Fitted pdf

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- The q -quantile of X is that value γ such that $\mathbb{P}(X \leq \gamma) = F(\gamma) = q$, for $0 < q < 1$. When $F(x)$ has an inverse, we can write $\gamma = F^{-1}(q)$.
 - Median: 50% quantile.
 - In financial risk management, quantile of the profit-and-loss of a portfolio is also called Value-at-Risk (VaR).

- To make Q-Q plots, given the data $\{x_1, \dots, x_n\}$ and the fitted distribution with CDF $F(x)$:
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[†]Originally, $F_n(x_{(i)}) = \frac{i}{n}$; adjustment is made such that $\tilde{F}_n(x_{(i)}) := F_n(x_{(i)}) - \frac{0.5}{n} = \frac{i-0.5}{n}$ is used.



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 - Q-Q plot displays $x_{(1)}, \dots, x_{(n)}$ vs. $F^{-1}\left(\frac{1-0.5}{n}\right), \dots, F^{-1}\left(\frac{n-0.5}{n}\right)$.

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 - If the data is indeed generated from distribution $F(x)$, then

$$x_{(i)} \approx F^{-1}\left(\frac{i - 0.5}{n}\right),$$

so the plot will be approximately a straight line with slope 1.

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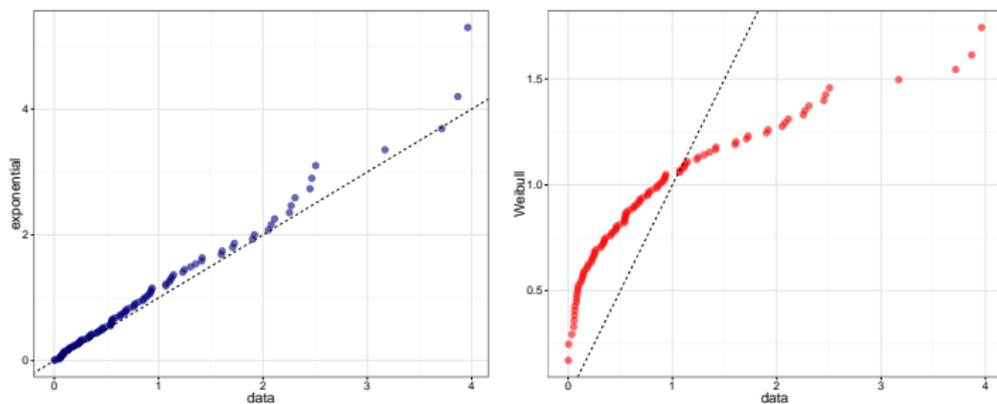


Figure: Examples of Q-Q Plot (from [ZHANG Xiaowei](#))

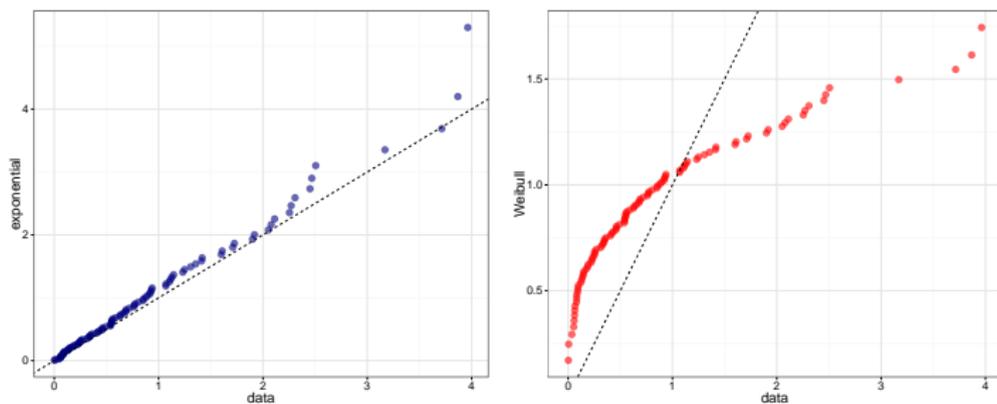


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- The observed values will never fall exactly on a straight line
- The ordered values are not independent because they are ranked. Hence, if one point lies above the line, it is likely that the next one will too.
- The values at the extremes have a much higher variance than those in the middle. So greater discrepancies can be acceptable at the extremes; linearity in the middle is much more important.

- **Probability-Probability (P-P) plot** compares $\tilde{F}_n(x_{(1)}), \dots, \tilde{F}_n(x_{(n)})^\dagger$ vs. $F(x_{(1)}), \dots, F(x_{(n)})$.

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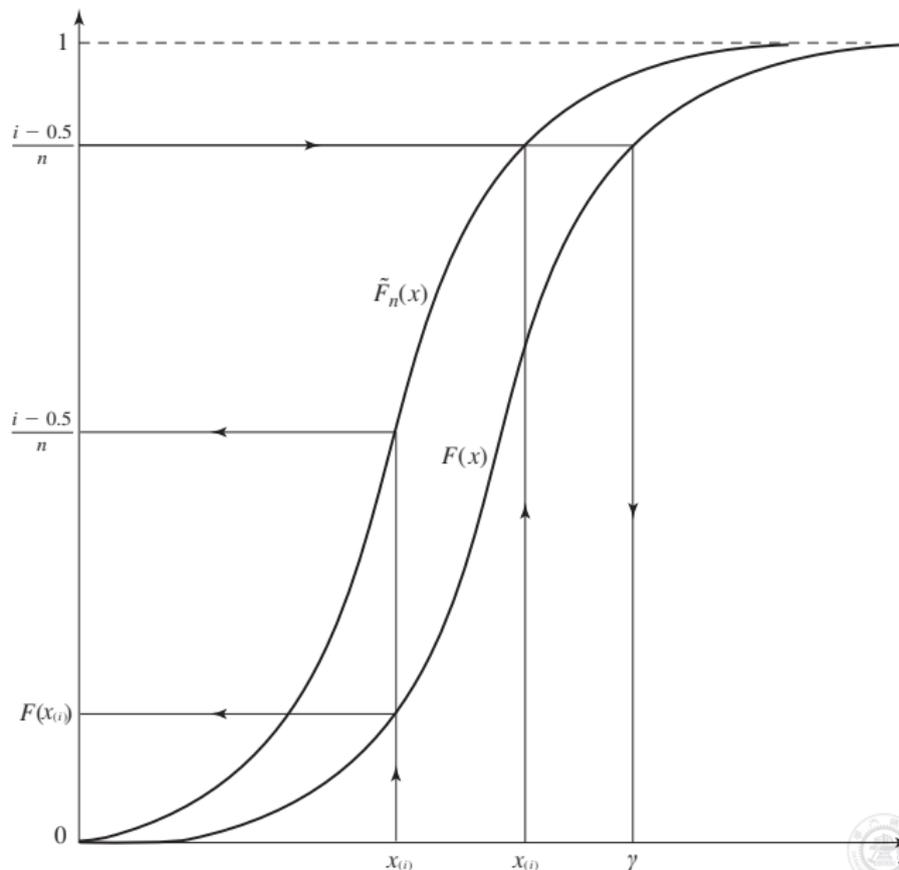
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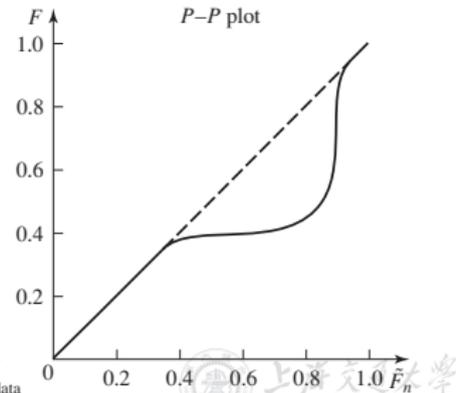
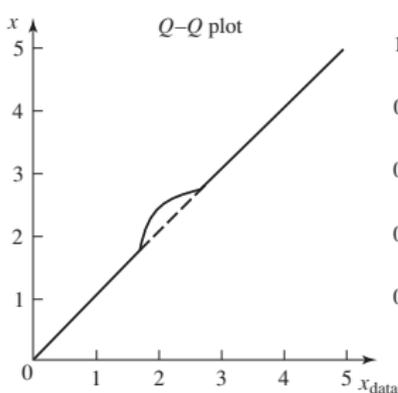
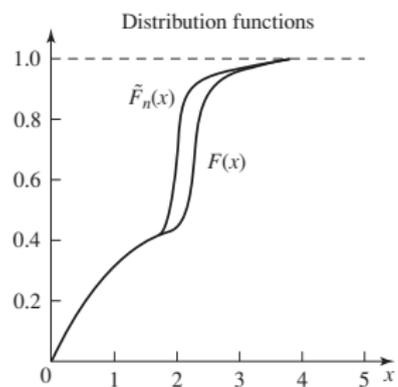
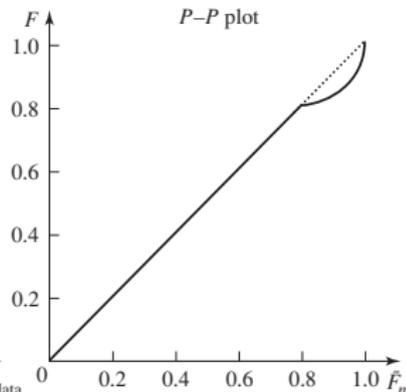
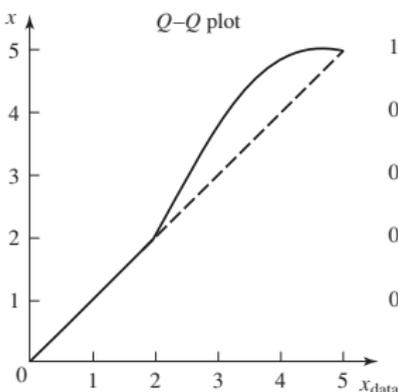
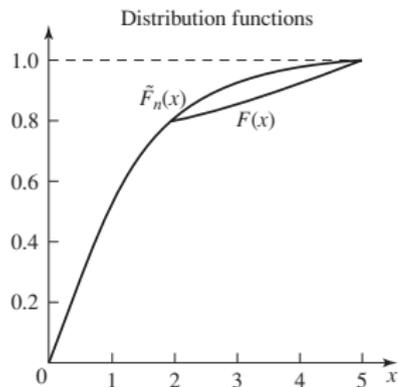
- **Probability-Probability (P-P) plot** compares $\tilde{F}_n(x_{(1)}), \dots, \tilde{F}_n(x_{(n)})^\dagger$ vs. $F(x_{(1)}), \dots, F(x_{(n)})$.
- It is valid for both continuous and discrete fitted distribution.
- If the data is indeed generated from distribution $F(x)$, then

$$\tilde{F}_n(x_{(i)}) \approx F(x_{(i)}),$$

so the plot will be approximately a straight line with slope 1.

[†] Note that $\tilde{F}_n(x_{(i)}) = \frac{i-0.5}{n}$.





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Truth \ Decision	reject H_0	fail to reject H_0
	H_0 is true	type I error
H_1 is true	correct	type II error

- A hypothesis test only directly controls the type I error.
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 - *p*-value is smaller than some specified α , or, equivalently,
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 - If the likelihood is very small (i.e., p -value is very small), then H_0 is unlikely to be true (reject H_0);
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 - Question: How large is too large? (i.e., what is the rejection region?)



- View the test statistic R as a random variable.
 - Since we assume the collected data is one observed random sample from some unknown distribution, if we conduct the study multiple times, the values of the statistics will be different because the collected data will be different.
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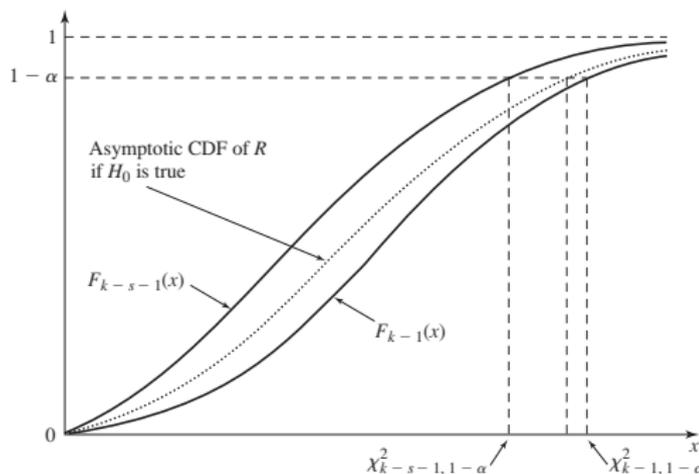
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- If H_0 is true, then R **approximately** follows the chi-square distribution with $k - s - 1$ degrees of freedom (i.e., χ_{k-s-1}^2 distribution) when sample size n is large.

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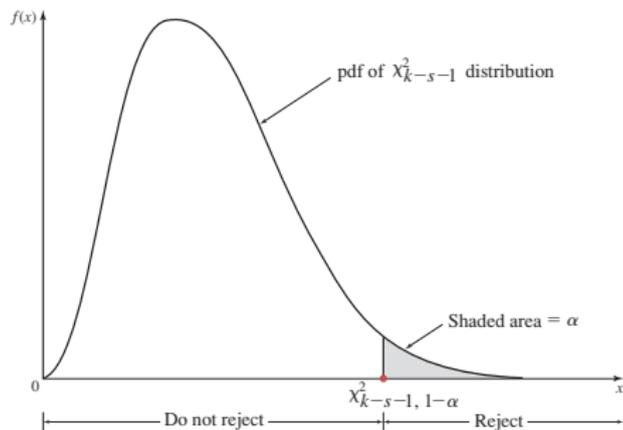
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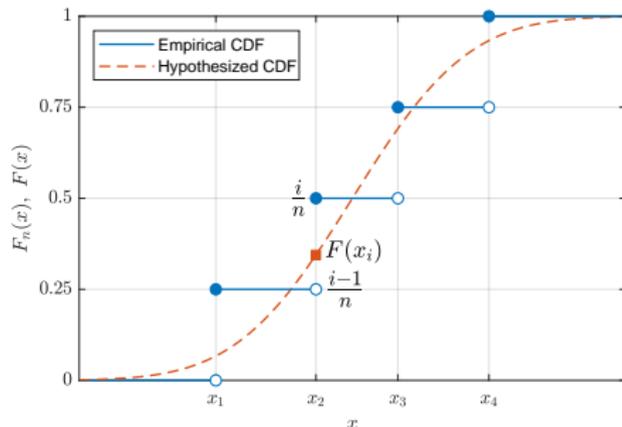


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 - **Major drawback:** The validity and power of chi-square test are affected by the number and size of the chosen intervals, while there is no clear prescription for such selection.

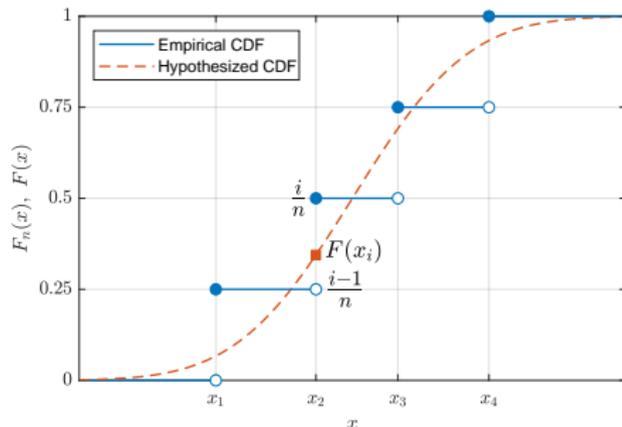
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- In the absence of a definitive guideline for choosing the intervals, it's usually recommended to make E_i equal (or approximately equal) and no less than 5, for all intervals.

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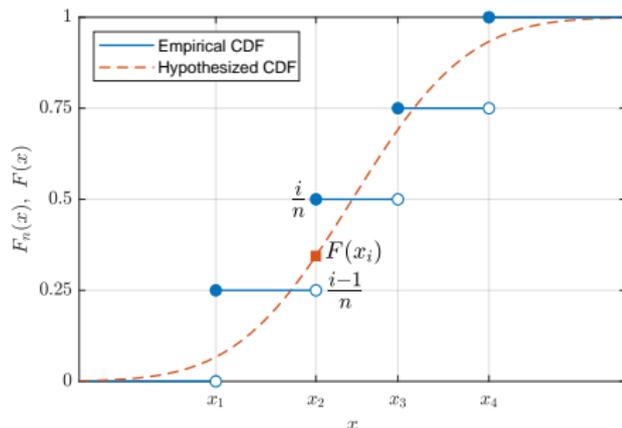


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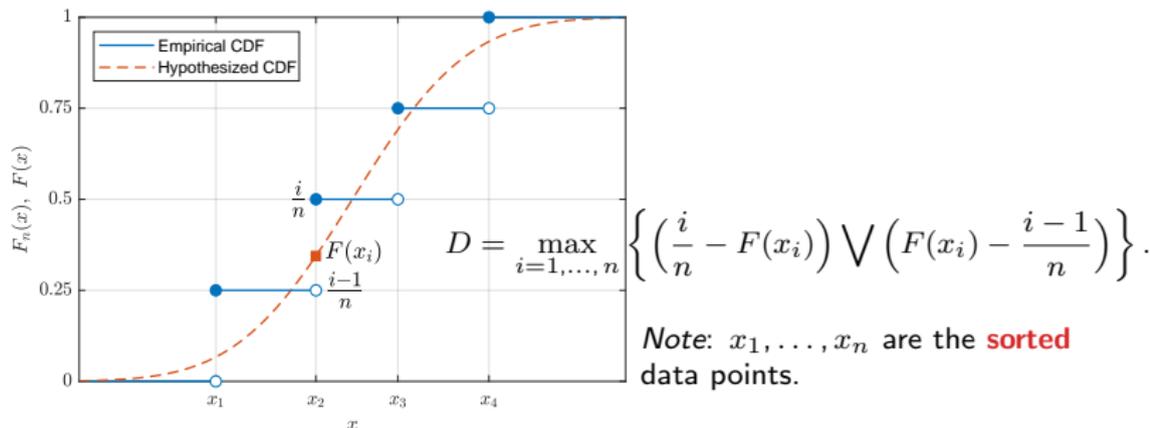
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 - Numerical tables and accurate approximation are available.
- If $F(x)$ is CDF of distribution such as normal, exponential, or Weibull, and parameters are estimated via MLE (except for normal σ^2 , which is estimated by S^2):
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- Advantage of K-S test:
 - It does not require us to group the data in any way, so no information is lost and no troublesome selection is faced.
 - It is valid (exactly) for any sample size, whereas chi-square test is valid only in an asymptotic sense.
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 - When applicable, its computation of p -value and rejection region is usually complicated.
- K-S test is relatively more convenient to be used in a case where the hypothesized distribution is continuous and no parameter is estimated. For example:
 - Test random number generators.
 - Test a Poisson process (more details later).

- Comments on p -value:
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 - Different statistical tests may give different p -values.
 - Whether or not you reject H_0 also depends on the significance level α chosen by yourself.

- Comments on general goodness-of-fit tests:
 - If very little data are available, then a goodness-of-fit test is unlikely to reject any candidate distribution.
 - No enough evidence to reject H_0 .
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 - H_0 is virtually never exactly true, and even a tiny departure from the hypothesized distribution will be detected for large n .
 - Do not have blind faith in goodness-of-fit tests!
 - Failing to reject a candidate distribution should be taken as only **one piece of evidence** in favor of that choice.
 - Rejecting a candidate distribution should be taken as only **one piece of evidence** against the choice.

- Graphical Methods vs. Statistical Tests
 - Graphical methods *qualitatively* measure the fitting goodness, while statistical tests *quantitatively* measure the fitting goodness.
 - Statistical tests measure the lack of fit by summary statistics, while graphical methods show where the lack of fit occurs (body, left tail, right tail) and allow users to decide whether it is important.
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- When no model fits the data satisfactorily, we may end up with the empirical distribution.

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 - It recommends the “best” distribution in its library based on summary measure like the p -value (and perhaps other factors such as discrete or continuous, bounded or unbounded).
- Always keep the following in mind when using such an option:
 - The software might know nothing about the physical basis of the data.
 - Automated best-fit procedures tend to choose the more flexible distributions (gamma over Erlang, Weibull over exponential).
 - But, close conformance to the data does not always lead to the most appropriate input model (overfitting).
 - The limitation of summary measure like p -value.
 - View the automated distribution selection as one suggestion, inspect it using graphical methods, and remember that *the final choice is yours*.

- All the graphical methods and statistical tests can be used to check the uniformity of a random number generator (RNG).
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 - Method 2: Test if $\text{Unif}(0, T)$ can fit the data $\{s_1, \dots, s_n\}$ well. (**Why?**)

- All the graphical methods and statistical tests can be used to check the uniformity of a random number generator (RNG).
 - ① Generate a sequences of numbers (as many as you want) using the RNG.
 - ② Check if $\text{Unif}(0, 1)$ fits the data well enough.
- Poisson-Process Test
 - Suppose we observe an arrival process for a time interval $[0, T]$, where T is a constant decided before we start our observation.
 - We see n arrivals during $[0, T]$ with arrival times s_1, s_2, \dots, s_n , and want to check if Poisson process is a good model for it.
 - Method 1: Test if an exponential distribution can fit the data $\{s_1, s_2 - s_1, \dots, s_n - s_{n-1}\}$ well.
 - Method 2: Test if $\text{Unif}(0, T)$ can fit the data $\{s_1, \dots, s_n\}$ well. (**Why?**)
 - Given $N(T) = n$, the n arrival times S_1, \dots, S_n have the same distribution as n independent RVs from $\text{Unif}(0, T)$ that are **sorted**.

- 1 Introduction
- 2 Data Collection
- 3 Identifying Distribution
 - ▶ Physical Basis of Distributions
 - ▶ Histogram and Bar Chart
- 4 Distribution Fitting
 - ▶ Method of Moments
 - ▶ A Simple Variation of MoM
 - ▶ Maximum Likelihood Estimation
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 - ▶ Graphical Methods
 - ▶ Statistical Tests
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- 6 An Illustrative Example

An Illustrative Example

- Suppose we want to build a statistical model for the life time (i.e., time to failure) of a electronic component at 1.5 times the nominal voltage.

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① Data Collection.

- Perform life tests on a random sample ($n = 50$) of electronic components and record their lifetime, in days:

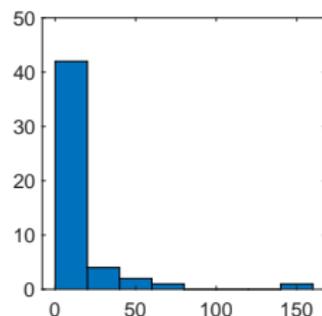
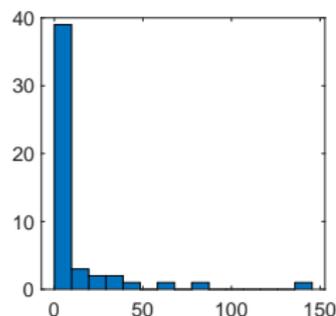
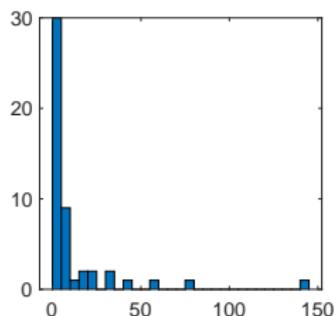
79.919	3.081	0.062	1.961	5.845
3.027	6.505	0.021	0.013	0.123
6.769	59.899	1.192	34.760	5.009
18.387	0.141	43.565	24.420	0.433
144.695	2.663	17.967	0.091	9.003
0.941	0.878	3.371	2.157	7.579
0.624	5.380	3.148	7.078	23.960
0.590	1.928	0.300	0.002	0.543
7.004	31.764	1.005	1.147	0.219
3.217	14.382	1.008	2.336	4.562

② Identifying Distribution.

- Lifetime, although recorded to three-decimal-place accuracy, is a positive continuous variable.
- For this life time, naturally, exponential and Weibull are considered.

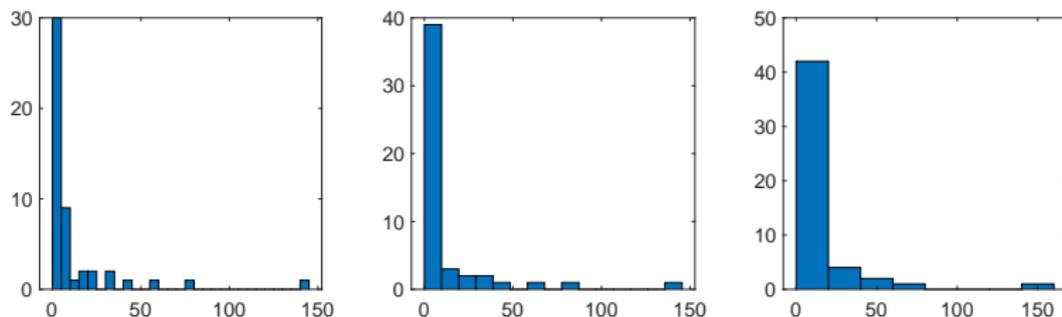
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- We decide to first try exponential distribution family $\text{Exp}(\lambda)$.

3 Distribution Fitting.

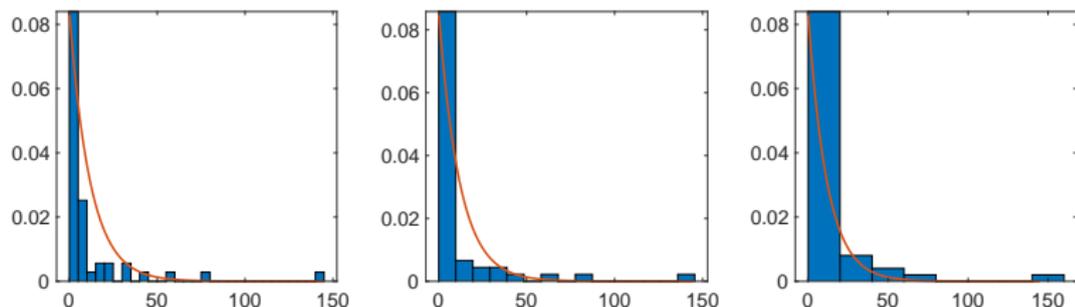
- Recall Example 2, MoM (or its variation) and MLE yield the same estimator for λ , which is $\hat{\lambda} = \frac{n}{X_1 + \dots + X_n}$.
- Plug the data in, and the estimate of λ is 0.084.

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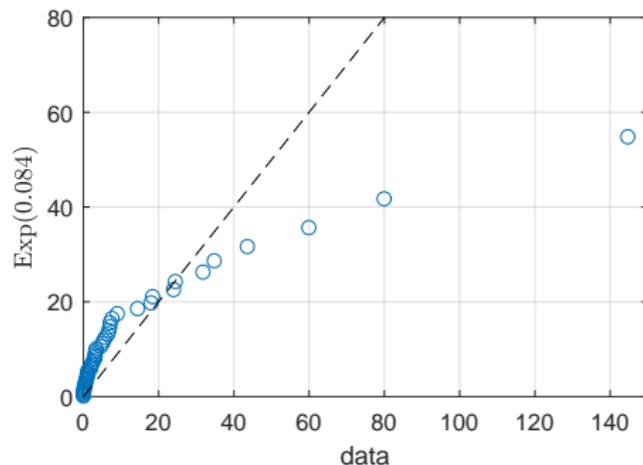
4 Goodness of Fit.

- Scaled histogram vs. pdf of $\text{Exp}(0.084)$.



④ Goodness of Fit.

- Q-Q plot.



4 Goodness of Fit.

- Chi-square test (H_0 : The data come from $\text{Exp}(0.084)$).
Number of estimated parameters is $s = 1$.

An Illustrative Example

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Choose intervals (make E_i equal).

<i>Class Interval</i>	<i>Observed Frequency</i> O_i	<i>Expected Frequency</i> E_i	$\frac{(O_i - E_i)^2}{E_i}$
[0, 1.590)	19	6.25	26.01
[1.590, 3.425)	10	6.25	2.25
[3.425, 5.595)	3	6.25	0.81
[5.595, 8.252)	6	6.25	0.01
[8.252, 11.677)	1	6.25	4.41
[11.677, 16.503)	1	6.25	4.41
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Hence, at almost any practical level of significance, e.g., $\alpha = 0.05$, $\alpha = 0.01$, we will reject H_0 .